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Theory of the filtrations of the sigma-fields and its applications

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We discuss mainly commutative case

1. A filtration is the decreasing sequence of the sigma-fields of measurable sets of the space (X, μ) :

$$\mathfrak{F}=\mathfrak{A}_0\supset\mathfrak{A}_1\supset\mathfrak{A}_2\ldots$$

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Each sigma-field canonically corresponds to the measurable partition of the space (X, μ) : each elements of sigma-field $\mathfrak A$ are the sets which are consist with the blocks of that partition. So filtration uniquely $\mod 0$ generates the decreasing sequence of the measurable partitions $\{\xi_n\}_n$:

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Another type of description of the filtration as decreasing sequence of subalgebras of functions (or, equivalently — sequence of the operators of mathematical expectation on sigma-fields \mathfrak{A}_i):

$$L^{\infty}(X,\mu)\supset L^{\infty}(X_{\xi_1},\mu_{\xi_1})\dots$$
 or $Id>P_{\xi_1}>P_{\xi_2}\dots$

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- in the theory of C^* -algebras and combinatorics, as tail filtrations of the path spaces of equipped \mathbb{N} -graded locally finite graphs (Bratteli diagrams). The space of paths $T(\Gamma)$ is the same as Markov compact(not stationary in general) and we can use terminology of the theory of Markov processes.

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Many problems about filtrations have appeared in ergodic theory, (decreasing sequences of measurable partitions = filtrations of of sigma-fields in the standard measure space), theory of stochastic processes (martingale theory), boundaries (Martin, exit, Poisson-Furstenberg etc.), theory of approximation of the group actions; VWB-Ornstein criteria etc.



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The cotransition probability is a cocycle on the equivalence relation: $\beta(x,y) = \frac{\mu^C(x)}{\mu^C(y)}$. In Markov case β depends on the last joint coordinate of x and y.

- 1) Measure-theoretical posing of problem.
- To decompose given Markov measure onto ergodic components of filtrations or to find Poisson-Boundary of the given process (Harmonic analysis)
- 2) Topological posing of the problem.

To find the ABSOLUTE (Entrance-Exit boundaries) the set (simplex) of all probability measures on the standard Borel space with given filtration — systems of cotransition probabilities.

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Example: Absolute of the Random Walk on the free groups

Difference with Poisson-Furstenberg boundary EXAMPLE: Absolute of free group (with A.Malyutin) (on the blackboard)

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Examples. Random walk in random environment.

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STANDARDNESS AND HIGHEST 0-1 LAWS

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If we choose a trace χ (central measure on \mathcal{A}) then we obtain a filtration of the past of Markov measure with maximal entropy.

Tail filtration of AF-algebras and its commutative counterpart

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where

$$\mathcal{A}_n = \sum_{u \in \Gamma_n} \bigoplus \mathbf{1}_{\lambda(u)} \bigotimes \mathcal{A}_{n,u},$$

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and $\lambda(u)$ is dimension of u= number of paths form \emptyset to u. The filtration $\{A_n\}$ is the sequences of the commutants.

The commutative subalgebra GZ(=Gelfand-Zetlin) of AF-algebra $\mathcal A$ inherit filtration on $\mathcal A$ and if we fix a central measure χ we obtain the filtration in $L^\infty_\chi(T(\Gamma))$. This is the same filtration which we define in the space of paths.

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- (Corresponding Bratteli diagrams, Tower of measures.

Questions:

Is it true that each dyadic ergodic filtration of measure space is Bernoulli (or product filtration?

The same question for for AF-algebra:

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General Problem To classify the tail filtrations, in particulary dyadic filtrations, in commutative and non-commutative cases.

Consider the main partial case, so called *dyadic filtrations*. In measure-theoretic case was studied from the end of 60-th. Dyadic filtration. For *AF*-algebras:

Definition A filtration $\{A_n\}$ of AF-algebra A called dyadic if $\bigcap_n A_n = \{const 1\}$ and for all $n \in \mathbb{N}$:

$$\mathcal{A}\cong M_{2^n}(\mathbb{C})\bigotimes \mathcal{A}_n \quad \forall n\in\mathbb{N}, \text{and} \quad \bigcap_n A_n=\{\textit{const}\} \quad (*)$$

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Example: The *standard* dyadic filtration of AF-algebra is a dyadic filtration which is isomorphic to the filtration of infinite tensor product: $\mathcal{A} = \bigotimes_{1}^{\infty} M_2(\mathbb{C}) = (M_2(\mathbb{C}))^{\otimes \infty}$:

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(Dyadic filtration of AF-algebra (when exists) is an analogue of the notion of countable tensor product of algebra $M_2(\mathbb{C})$)

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as the tail filtration in the path space $T(\Gamma)$ of an equipped graded graph Γ ;

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more generally — filtration in the Cantor space (without measure). The filtration called "discrete" if the conditional filtration $\{\mathfrak{A}_i/\mathfrak{A}_n; i=0,1,\ldots n-1\}$ over sigma-field \mathfrak{A}_n for all n are filtration (hierarchy) of the finite space with measure.

Let $\xi_n, n < 0$ sequence of random variables. The sigma-algebra $\mathfrak{A}_n = << \xi_k, k \leq -n >>$ - sigma-algebra of the past:

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Filtration in the measure space called ergodic, or regular, or Kolmogorov, or has zero-one-law — if $(\mathfrak{N}$ is trivial sigma-field):

$$\bigcap_{n}\mathfrak{A}_{n}=\mathfrak{N},$$

is trivial sigma-fields.



Bernoulli filtration in commutative case

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Definition

Homogeneous standard filtrations of the measure space is a filtration which is isomorphic in measure theoretic sense to Bernoulli filtration (or filtration of product type) with arbitrary components: filtration on the space $\prod_{n=1}^{\infty}(\mathbf{r}_n,m_{r_n})$, where \mathbf{r}_n is finite space with $r_n\in\mathbb{N}\smallsetminus 0$ points, and m_k a uniform measure on \mathbf{r}_n . Dyadic filtration: $r_n\equiv 2$

We will give a general definition of standard filtration later.

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Homogeneous filtration whose number of points in one elements of partition ξ_n equal to r^n called r-adic filtration (**dyadic** for r = 2).

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A concrete discrete filtration called *Markov filtration* if is the past of a one-sided Markov chain with discrete time, with finite list of transition probabilities and arbitrary state space. Each discrete filtration can be realized as Markov one.

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The group D_n of all automorphisms of n-level dyadic tree with 2^n points acts on each block $C: |C| = 2^n$ of partition $\xi_n, 1, \ldots$ and consequently acts on the functions on C.

Let $\eta = \{B_1, B_2, \dots B_k\}$ -an arbitrary finite measurable partition of [0,1] with k blocks. On each block $C \in \xi_n$ define a function $f_n: C \to \mathbf{k}: f_n(c) = i \in \mathbf{k}: c = C \cap B_i$. Denote the orbit of action of the group D_n on the vectors $\{f_n(c)\}_{c \in C}$ as $Orb_n(C)$. Finally define on the set of orbits of the group D_n the metric r_n : $r_n(O_1, O_2) = \min_{x \in O_1, y \in O_2} \rho_n(x, y)$, where ρ_n is Hamming metric on the vectors with value in \mathbf{k}

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Criteria of standardness Dyadic filtration $\{\xi_n\}$ is Bernoulli (or product-type or standard) iff \forall finite measurable partition η

$$\lim_{n} \int_{[0,1]\times[0,1]} r_{n}(Orb_{n}(C), Orb_{n}(C')) dCdC' = 0.$$

It is natural to fix a trace of algebra and discuss about the image of AF-algebra in the corresponding II_1 representation. It is possible to have different answer for different traces.

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Criteria for homogeneous for general homogeneous filtrations, iteration of Kantorovich metric (intrinsic metric) It is make sense in the case of AF-algebras to distinguish weak and strong standardness: weak means that in all II_1 factor representations the image of algebra is standard in the sense which is described below.

Two filtrations $\{\mathfrak{A}_n\}_{n=0}^\infty$ and $\{\mathfrak{A}'_n\}_{n=0}^\infty$ called finitely isomorphic if for each N the finite fragments for $n=0,1\ldots N$ of its are metrically isomorphic.(For each n there exists mp automorphism T_n for each k < n $T_n \mathfrak{A}_k = \mathfrak{A}'_k\}$.

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The problem of classification of discrete Markov filtrations in the category of measure spaces or in other categories is deep and quite topical.

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AF-algebra called standard if for any ergodic central measure tail filtration if standard in the previous sense.

Examples of standard graphs: Pascal, Young etc. Concentration, Limit shape theorem.

Definition

The result of transferring the metric ρ_X on the space X to the Borel space Y along the equipped map

$$\phi: X \to Y$$

is the metric ρ_Y on Y defined by the formula

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Standardness is generalization of independence ("eventually independence").



We formulate the criteria in terms of past of Markov processes $\{X_n, n \leq 0\}$

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Theorem(standard criteria). The Markov chain $\{x_n, n \leq 0, x_n \in X_n\}$ (X_n is the state space at moment N and it could be depend on n) the filtration of the past of it called standard if $\forall \epsilon > 0, \exists N \in \mathbb{N} \quad \forall n < -N \text{and} \quad A_n \subset X_n Prob(A) > 1 - \epsilon$ with the following property

$$E_{x_n,x_n'}$$
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$$E_{x_n,x_n'}\mathsf{Dist}(\mathsf{Prob}(.|x_n),\mathsf{Prob}(.|x_n'))<\epsilon,x_n,x_n'\in X_n$$

where Dist is a Kantorovich-like metric between conditional measures $Prob(.|x_n)$ as a measures "on the trees of the future" (see below).

Theorem(V-71) The standard dyadic (more generally, homogeneous) filtration is isomorphic to Bernoulli filtration (=the filtration of the past of the classical Bernoulli scheme).

The condition in the definition asserts the convergence in probability of the conditional measures in the very strong (unform) metric which take care about hierarchy of the future of the trajectories. This is further strengthen of the martingale theorem which asserts the simple convergence of conditional structures and took place for all ergodic filtrations.

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There is no limit distribution but there are very strong concentration of the many dimensional distributions up to coupling which preserve the hierarchy of conditional measures.

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Definition

A filtration $\{\mathfrak{A}_n\}_{n\in\mathbb{N}}$ is called standard if

$$\lim_{n \to \infty} \int \int_{X \times X} \bar{\rho}_n(x, y) d\mu(x) d\mu(y) = 0$$
 (1)

for any initial metric ρ .

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EVANESCENT (or VIRTUALLY) measure metric spaces and Gromov-V. invariants of m-m-spaces.

Theorem on classification of the measure-metric spaces.

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Consider a map

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("matrix distribution") is the complete invariant of the triple τ w.r. to measure preserving isometry. The map $\tau--->D_{\tau}$ is continuous in the right sense. What happened if there is a sequence of m-m spaces which does not converge?

Virtual matrix distributions.

